Drones and Water Quality

Ottawa County Ninth Annual Water Quality Forum

John Koches Annis Water Resources Institute November 7, 2014 10/21/2014

NEW YORK

Drones and Everything After -- NYMag

nymag.com

Daily Intelligencer | the future | October 5, 2014 9:05 p.m.

Drones and Everything After

By Benjamin Wallace-Wells



Drones And Everything After The flying, spying, killing machines that are turning humans into superheroes. By Benjamin Wallace-Wells Illustrations by Andrew Rae



"I want to buy...a drone" now fourth most popular Google autocomplete term for that phrase

Posted by Chris Anderson on October 5, 2014 at 9:32pm 🛛 🔀 Send Message 🛛 👗 View Blog

From Guns to Drones

Recurring autofill terms when Google users start a search.

I want to buy...

First Quarter, 2011	First Quarter, 2012	First Quarter, 2013	First Quarter, 2014	Second Quarter	Third Quarter
a house	you something	a g <mark>u</mark> n	a house	a house	a house
a car	a car	a car	stock	stock	a car
stock	stock	stock	a dog	a car	stock
a gun	something	something	a car	something	a drone

Source: ConvergEx Group

Google now gives "a drone" as the fourth most popular answer to the search term "I want to buy..."! Data from the New York Times

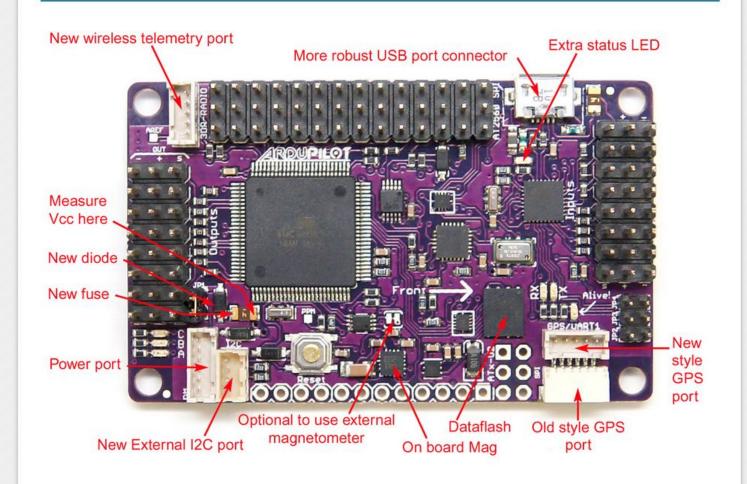
Drones vs. Unmanned Aerial Systems

Overview – What are we talking about
Rules and Regulations
General Applications
Research Applications

Aquatic Science Research

APM 2.6

- APM 2.6 is a revision of the APM that makes use of an external magnetometer (compass).
- The APM 2.6 has no on board compass, and is optimized for vehicles where the compass should be placed as far from power and motor sources as possible to avoid magnetic interference.
- APM 2.6 is designed to be used with the 3DR GPS uBlox LEA-6 with Compass module.
- The GPS/Compass module may be mounted further from noise sources than the APM itself.
- APM 2.6 requires a GPS unit with an on board compass for full autonomy.
- For information on installing a 3DR GPS uBlox LEA-6 with Compass, visit (Here!).
- Details APM 2.0



APM Autopilot Suite

Hardware — Firmware — Software — Community

Hardware- The embedded systems and peripheral sensors that 3DRobotics designs, manufactures, and sells.

Think of hardware as the brain, eyes, ears, etc.

Almost any mobile machine can be transformed into a robot, by simply integrating a small hardware package into it.



Firmware- The "skill set" code running on the hardware, which configures it for the kind of vehicle you've put it in. You choose the firmware and vehicle that match your mission: Plane, Copter, Rover...

The choice is yours — one autopilot for any mission. An easy firmware update is all it takes to repurpose your hardware into a different role.



Software- Your interface to the hardware.

Initial set-up, configuration, and testing. Mission-planning/operation, and postmission analysis.

Point-and-click intuitive interaction with your hardware, or advanced custom scripting for niche mission profiles. Options are everything with APM.





SPONSORED BY 3DRobotics

Table of Contents							
APM:Plane							
Introduction							
APM:Plane Current Release	Information						
Andu Diana Catura							
ArduPlane Setup Pixhawk Wiring and Quick S	tart *						
 Install Mission Planner* 	tart "						
 Load Firmware onto APM* 							
 APM USB Driver * 							
 Loading Firmware onto Pix 	nawk *						
 Load Firmware onto PX4 (M 							
 Qupgrade PX4 Firmware In 	stallation *						
 PX4 Firmware Installation L 	sing Qupgrade *						
 Connecting your RC gear 							
 Pixhawk and PX4 Compatil 		Receiver Systems *					
 Installing 3DR UBlox GPS + 	Compass Module *						
 First-time APM Setup 							
Checking the sensors							
 Reversing servos and settin MultipleAilerons 	ig normal/elevon mode						
 Automatic Flaps 							
 Differential Spoilers 							
 Arming Throttle 							
	Meaning *						

PLANE HOME INSTRUCTIONS DOWNLOADS COMMUNITY NEWS STORE **O** Search common-Mission Planner Ground Control Station **Table of Contents The GCS Flight Data Screen** Contents [hide] 0.1 The GCS Flight Data Screen 1 Guided Mode Intended heading (including crosstrack correction) Wireless telemetry connection (% bad packets) Heading direction Crosstrack error Direct line to current waypoint and turn rate (T) GPS time Bank angle Current heading Artificial Horizon Dir 0 (remember, this is the reverse of the aircraft's bank angle) Desired turn radius Air speed (Ground speed · 16 Track of recent if no airspeed sensor is fitted) travel GPS reported Air speed altitude Ground speed -Battery status -GPS reported Guick Actions Gauges Statue Telemetry Log Altitude (blue bar direction of travel is rate of climb) 87 (usually lags) alt GPS status groundspeed 49 wp_dist 122.013405 🔲 Tuning 🔛 Auto Pan Zoom 17.0 Latitude Longitude Altitude Current autopilot mode Distance to current waypoint ">" Current waypoint number The above is the main Ground Station view of the Mission Planner, showing the Heads-up Display (HUD). Once you have connected via

The above is the main Ground Station view of the Mission Planner, showing the Heads-up Display (HUD). Once you have connected via MAVLink over USB or wireless telemetry the dials and position on this screen will display the telemetry sent by APM.

Mission Planner

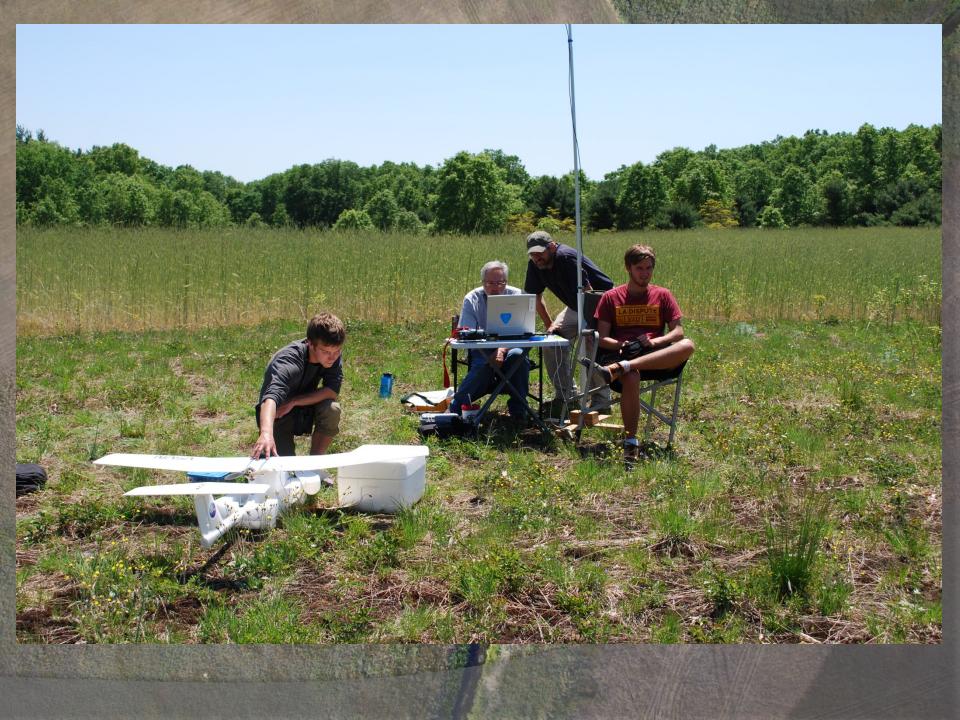


The Mission Planner, created by Michael Oborne, does a lot more than its name. Here are some of the features:

- Point-and-click waypoint entry, using Google Maps/Bing/Open street maps/Custom WMS.
- Select mission commands from drop-down menus
- Download mission log files and analyze them
- Configure APM settings for your airframe
- Interface with a PC flight simulator to create a full hardware-in-the-loop UAV simulator.
- See the output from APM's serial terminal

Please use the menus above for instructions and more information.







Rules and Regulations

 June 9, 1981- Advisory Circular 91-57 "Model Aircraft Operating Standards"

 February 13, 2007 – FAA says all model aircraft are "Unmanned Aircraft" and included as UAS. Public Aircraft, Civil Aircraft, and Model Aircraft

 February 14, 2012 – FAA Modernization and Reform Act of 2012

 December 30, 2013 – FAA announces six sites across the country where drones can be tested

Rules and Regulations – Cont.

 February 26, 2014 FAA releases "Busting Myths about the FAA and Unmanned Aircraft"

- March 6, 2014 Judge with National Transportation Safety Board strikes down FAA fine for TV commercial
- June 18, 2014 FAA releases "Interpretation of Special Rules for Model Aircraft"
- June 30, 2014 FAA unlikely to meet September 2015 deadline set by Congress

General Applications

A RO

- Military Drones
- Real Estate
- Intertainment
- Emergency Response
- Surveillance Law Enforcement
- Package Delivery
- Construction

Research Applications

Agriculture – Pest and Nutrient Management
Forest Management
Habitat Management / Conservation
Archeological Investigation
Air Quality Assessment
Weather and Climate Change

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Drones may provide big lift to agriculture when FAA allows their use



A drone lifts off at Kunde Family Vineyards near Santa Rosa, Calif. Ryan Kunde, a winemaker at DRNK Wines, flies his drones recreationally and has been testing drones with the goal of one day using them to help make decisions in the vineyard. (Discover Sonoma County Wine)

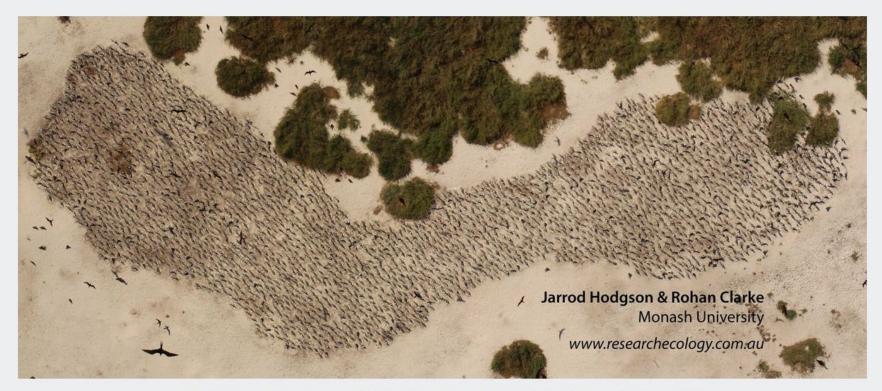
Los Angeles Times Business

This article is related to: Business, Agriculture, Dining and Drinking, Air Transportation Industry, Federal Aviation Administration, Lifestyle and Leisure, Amazon.com Inc.

By CHAD GARLAND

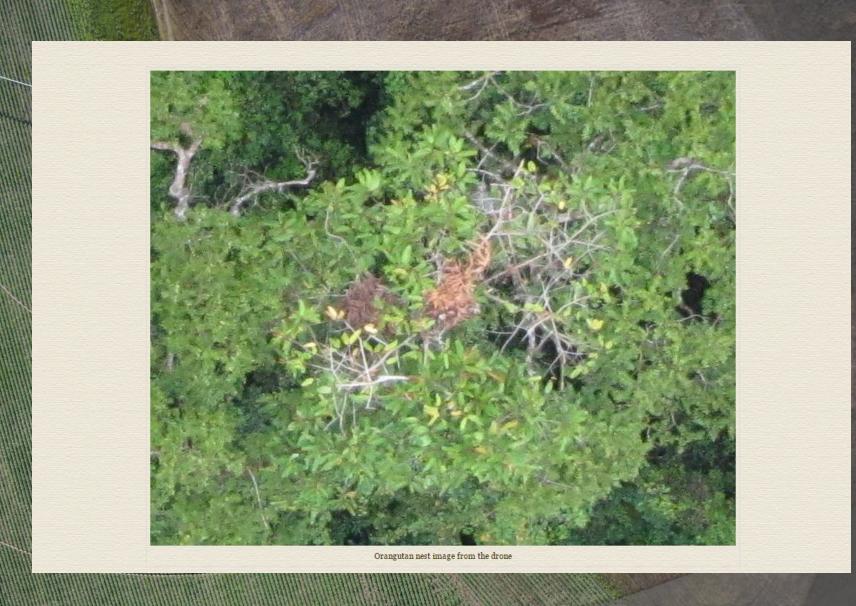
CONSERVATION DRONES FOR SEABIRD MONITORING

May 5, 2014 by ConservationDrones



Crested Tern colony on a remote island in north-western Australia photographed by a UAV.





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Marine Mammal Rescue

Ocean Wise

Marine Biodiversity

Whale Sightings

Marine Mammal Research

Shoreline Cleanup

Arctic Connections

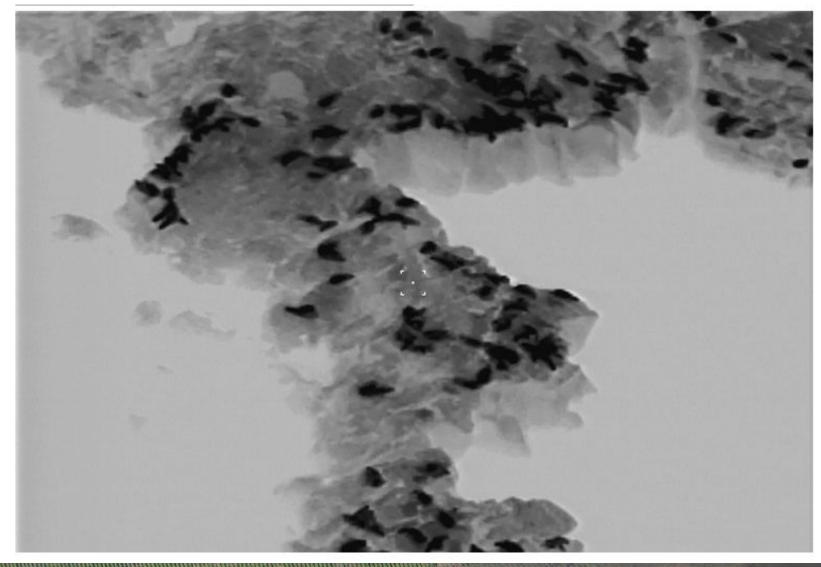
Vancouver Aquarium Uses Hexacopter to Track Killer Whales

by Vancouver Aquarium | Sep. 23, 2014



1

PHOTOS/COURTESY/ALASKA CENTER FOR UNMANNED AIRCRAFT SYSTEMS INTEGRATION





Dino drone helps track fossil finds



Drones for bones



Researchers at the Royal Tyrrell Museum are using technology to create massive digital maps of bone beds. Kevin Fleming explains...

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Colleen Schmidt, CTV Calgary Published Friday, September 19, 2014 12:54PM MDT Last Updated Friday, September 19, 2014 5:22PM MDT

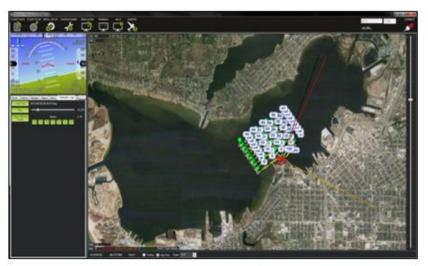
Aquatic Science Research

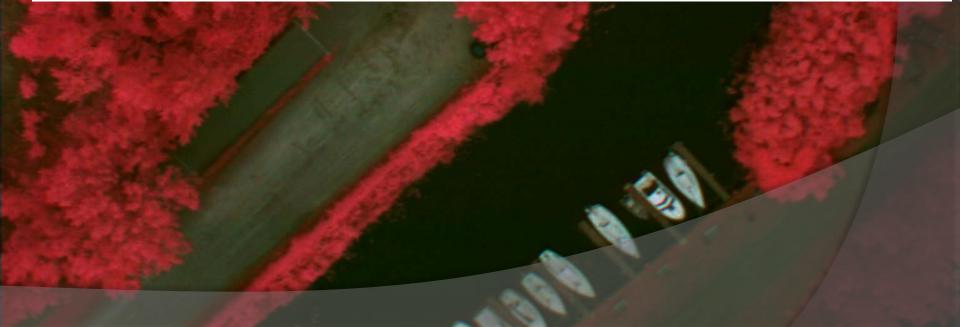
Hazardous Algal Blooms Lake Production / Trophic Status Septic Tank Discharge / Water Pollution Shoreline Erosion / 3D Assessments Airborne Pollution and Pathogens **Invasive Aquatic Plants** Habitat Assessment / Project Evaluation

Methods and Materials

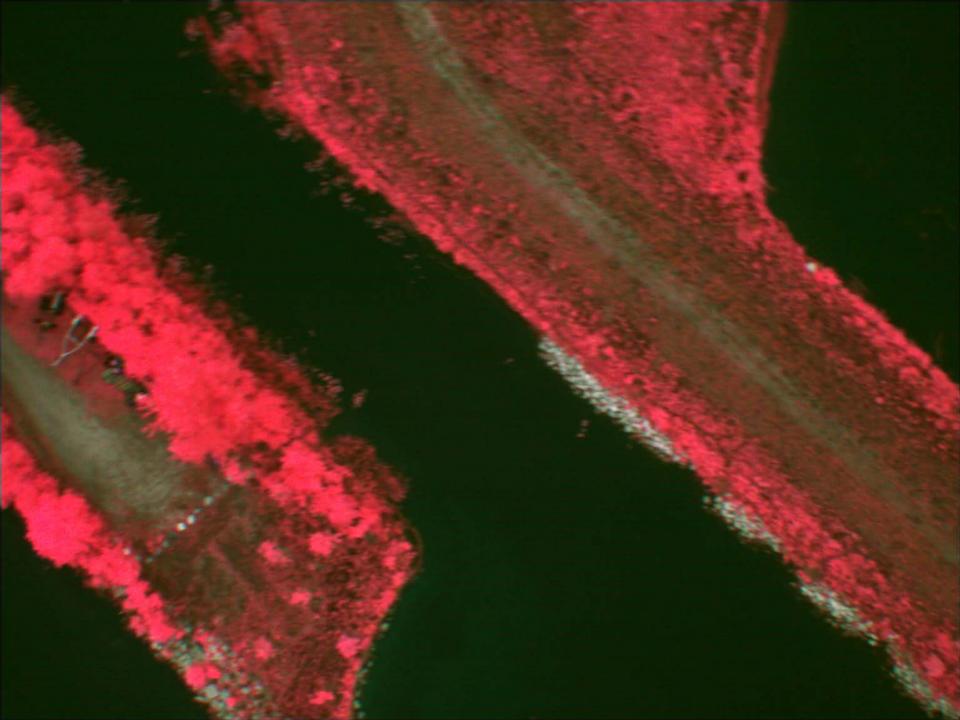
Study Area

The project study site was the 16.8 km2 Muskegon Lake in Muskegon County, MI. While the entire lake was up for consideration, the UAV missions and field sampling focused on the central region of the lake near the buoy-based observatory operated by Grand Valley State University's (GVSU) Annis Water Resources Institute (AWRI) (Figure 1).













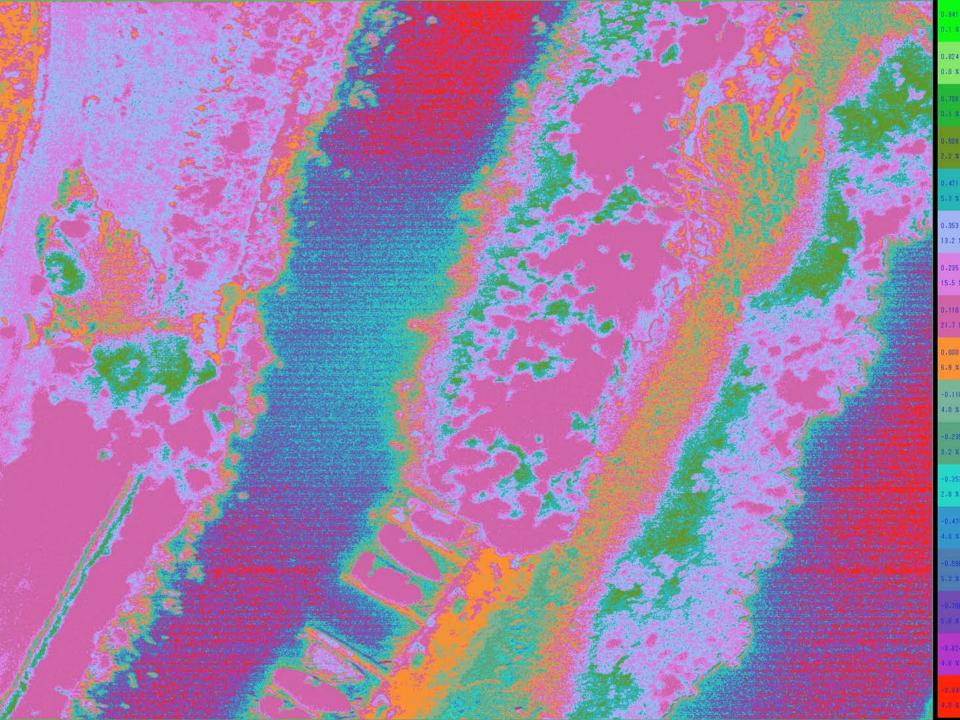


Table 1. Muskegon Lake Data for July 10 and August 5, 2013.

Sample	Chl	Avg NIR DN	Avg Red DN	Red/NIR	In(Red/NIR)	NIR/Red	In(NIR/Red)
B-1	16.8	1	52	77.615	4.352	0.013	-4.352
B-2	15.2	2	57	42.539	3.750	0.024	-3.750
B-3	15.7	5	51	15.225	2.723	0.066	-2.723
B-4	17	2	54	40.300	3.696	0.025	-3.696
B-5	14.3	10	58	8.657	2.158	0.116	-2.158
B-6	16.2	6	57	14.180	2.652	0.071	-2.652
B-7	17.5	3	59	29.354	3.379	0.034	-3.379
D-1	10.7	8	27	3.759	1.324	0.266	-1.324
D-2	12.9	8	25	3.480	1.247	0.287	-1.247
D-3	11.5	8	24	3.341	1.206	0.299	-1.206
D-4	10.3	7	23	3.659	1.297	0.273	-1.297
D-5	12	8	24	3.341	1.206	0.299	-1.206
D-6	11.8	8	25	3.480	1.247	0.287	-1.247
D-7	9.1	8	28	3.898	1.360	0.257	-1.360
D-8	12	8	28	3.898	1.360	0.257	-1.360
D-9	12.4	8	26	3.620	1.286	0.276	-1.286
D-10	12.9	9	28	3.465	1.243	0.289	-1.243
D-11	10.1	8	27	3.759	1.324	0.266	-1.324
D-12	9.6	8	27	3.759	1.324	0.266	-1.324
D-13	8.3	9	26	3.217	1.169	0.311	-1.169
D-14	10.7	9	26	3.217	1.169	0.311	-1.169
D-15	10.6	8	26	3.620	1.286	0.276	-1.286

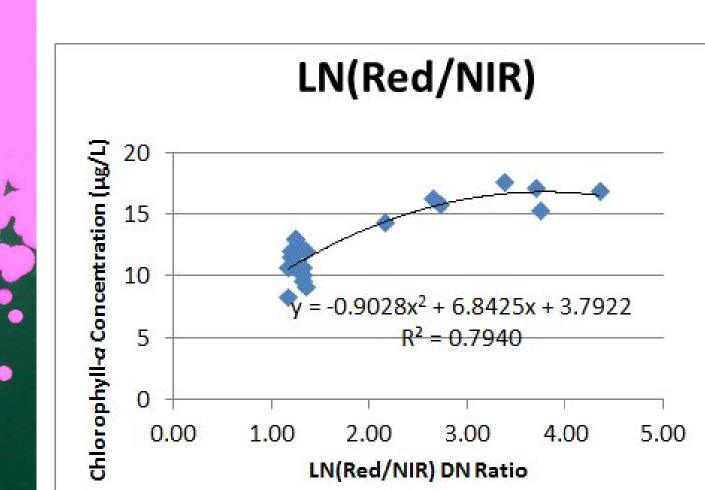
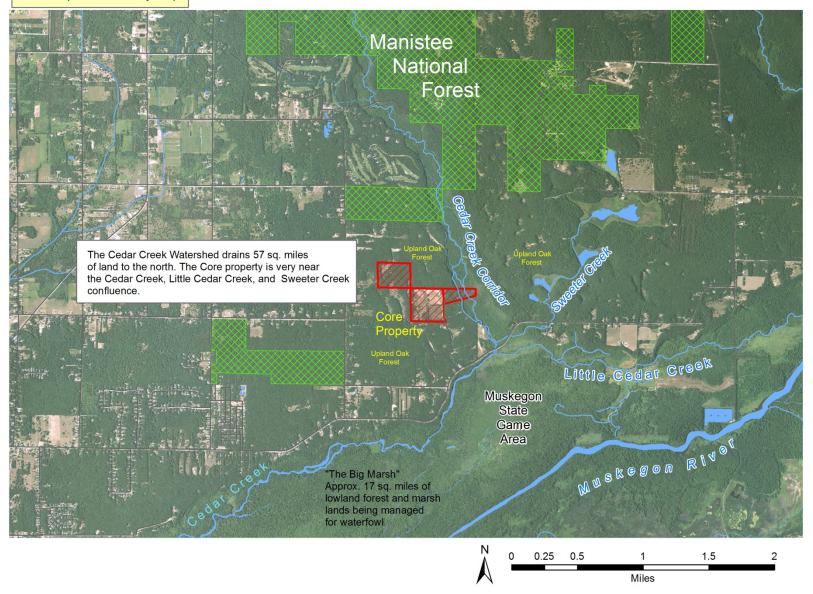
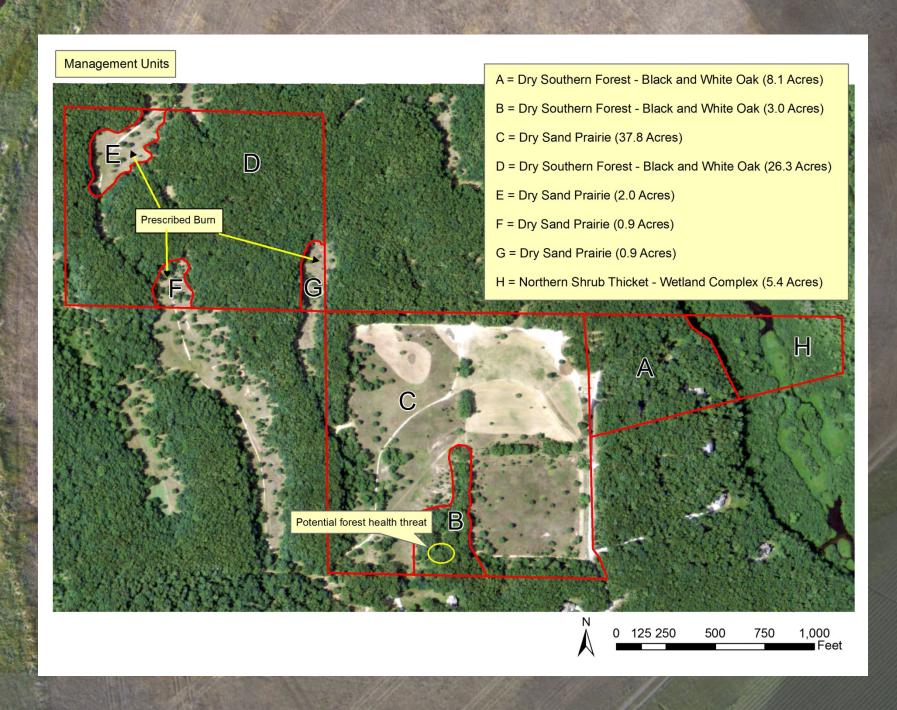


Figure 5. Chlorophyll concentration vs. LN(Red/NIR) and resultant trendline and R² value.

Landscape Connectivity Map







N



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